IN THE CLAIMS

Please amend the claims as follows:

1. (Currently Amended) A method of detecting motion in an area, the method comprising: receiving frames of the area;

using a high speed motion detection algorithm to remove frames in which a threshold amount of motion is not detected, wherein the high speed motion detection algorithm represents a selected portion of a frame with pixels in grey scale, and represents another portion of the frame with pixels in RGB; and

using a high performance motion detection algorithm on remaining frames to detect true motion from noise,

wherein the high performance detection algorithm operates on [[a]] <u>the</u> frame having pixels in grey scale for [[a]] <u>the</u> selected portion of the frame, and operates on the frame having pixels in RGB or other color domain for <u>the</u> another portion of the frame.

- 2. (Original) The method of claim 1 wherein the high speed detection algorithm operates in a compressed image domain.
- 3. (Original) The method of claim 1 wherein the high speed detection algorithm operates in an uncompressed image domain.
- 4. (Original) The method of claim 1 wherein the high performance detection algorithm operates in an image pixel domain.
- 5. (Original) The method of claim 4 wherein the high speed motion detection algorithm represents portions of images in grey scale pixels.
- 6. (Original) The method of claim 5 wherein portions of the image are represented in grey scale when such portions are not high in color content.

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- 7. (Previously Presented) The method of claim 1 wherein the selected portions of the images are low in color content.
- 8. (Original) The method of claim 7 wherein the portions are based on an initial set up.
- 9. (Previously Presented) The method of claim 1 wherein the selected portions are determined based on a real time assessment of dynamic change in the area.
- 10. (Original) The method of claim 1 wherein the threshold is predetermined.
- 11. (Original) The method of claim 1 wherein the area is a predetermined area.
- 12. (Previously Presented) The method of claim 1 wherein the frames comprise pixels, and where such pixels are grouped in blocks of pixels, each block being represented as an average or median in the color domain.
- 13. (Original) The method of claim 12 wherein the blocks of pixels are of different sizes.
- 14. (Original) The method of claim 13 wherein portions of the area requiring higher resolution to detect motion are represented by blocks of smaller number of pixels.
- (Original) The method of claim 13 wherein the number of pixels in the blocks is varied 15. based on depth of field.
- 16. (Currently Amended) A method of detecting motion in an area, the method comprising: receiving frames of the area;

using a high speed motion detection algorithm to remove frames in which a threshold amount of motion is not detected, wherein the high speed motion detection algorithm represents a selected portion of a frame with pixels in grey scale, and represents another portion of the frame with pixels in RGB;

using a high performance motion detection algorithm on remaining frames to detect true motion from noise, wherein the frames comprise pixels, and where<u>in</u> such pixels are grouped in blocks of pixels, each block being represented as a single average pixel; and

initializing a model of the area comprising multiple weighted distributions for each block of pixels.

- 17. (Original) The method of claim 16 wherein the frames comprise blocks of pixels, and wherein a number of weighted distributions per block is varied.
- 18. (Original) The method of claim 17 wherein the number of weighted distributions varies between 1 and 5.
- 19. (Original) The method of claim 17 wherein the number of weighted distributions is varied based on dynamics of motions or expectations.
- 20. (Original) The method of claim 16 wherein the model is based on N successive frames and the weight is based on a count.
- 21. (Original) The method of claim 16 wherein a predefined number of weighted distributions is selected for each block of pixels, and wherein the weights are normalized.
- 22. (Original) The method of claim 16 wherein if pixels in a new frame match the model, the model weights and distributions are updated.
- 23. (Previously Presented) The method of claim 16 wherein a (modified Jeffery's measure) is used to determine a match or non-match in the distributions.
- 24. (Original) The method of claim 16 wherein if a predetermined number of frames have pixels or blocks that do not match the model, the lowest weighted distributions of the pixels or blocks of a background are removed from the model and replaced by ones derived from a

foreground distribution once a derived number of sequences is reached within the last N successive frames.

- 25. (Original) The method of claim 16 wherein the high speed motion detection algorithm operates in a compressed image domain.
- 26. (Original) The method of claim 16 wherein the high speed motion detection algorithm operates in an uncompressed image domain.
- 27. (Currently Amended) A system for detecting motion in a monitored area, the system comprising:

means for receiving video images of the monitored area;

a fast video motion segmentation (VMS) module that rejects still images that do not portray any motion, wherein the fast VMS module represents a selected portion of a frame with pixels in grey scale, and represents another portion of the frame with pixels in RGB, and;

a robust VMS module that detects motion of an object in the monitored area; and a resource management controller that initializes, controls, and adapts the fast and robust VMS modules;

wherein the robust VMS module operates on [[a]] the frame having pixels in grey scale for a selected portion of the frame, and operates on the frame having pixels in RGB or other color domain for the another portion of the frame.